

# **DAO<sup>2</sup>: Overcoming Overall Storage Overflow in Intermittently Connected Sensor Networks**

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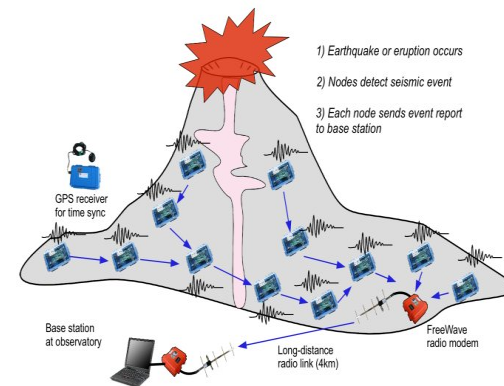
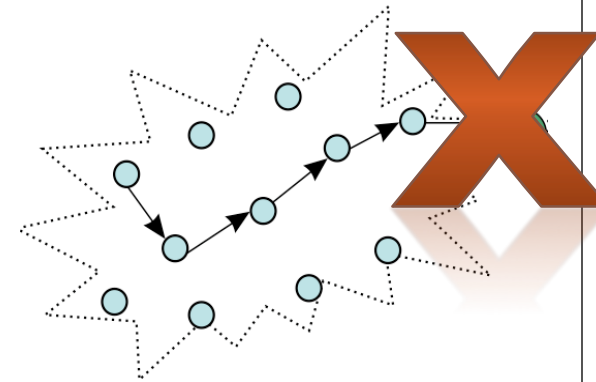
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# Outline

- ❖ ICSN and its overall storage overflow problem
- ❖ DAO<sup>2</sup> (Data Aggregation for Overall Storage Overflow)
- ❖ MTSW (Multiple Traveling Salesman Walks)
- ❖ Distributed DAO<sup>2</sup> algorithm
- ❖ Simulation results
- ❖ Conclusion and future work

# Intermittently Connected Sensor Networks (ICSN)

- ❖ Deepwater sensor networks for tactical surveillance, volcano eruption/glacial melting monitoring
- ❖ Not feasible to install base station in field
- ❖ Data generated and stored in the network, periodically uploaded via data mules or satellite links
- ❖ Data uploading opportunities are intermittently available



# Data Preservation in ICSN

- ❖ Non-uniform data generation and limited storage capacity

- ❖ **Data nodes**

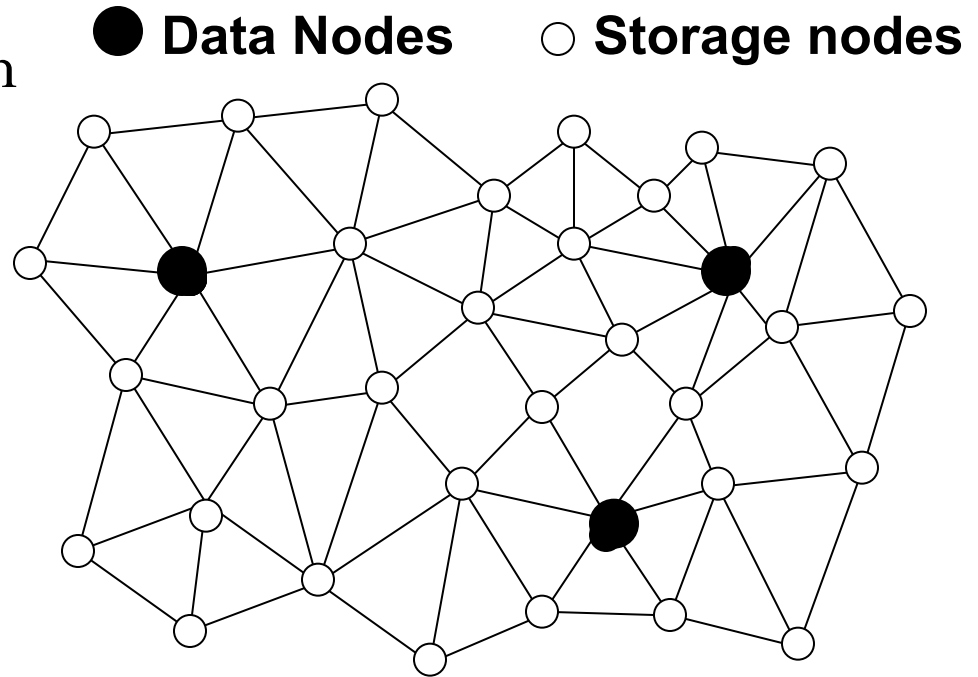
  - ❖ Storage-depleted

  - ❖ Overflow data

- ❖ **Storage nodes**

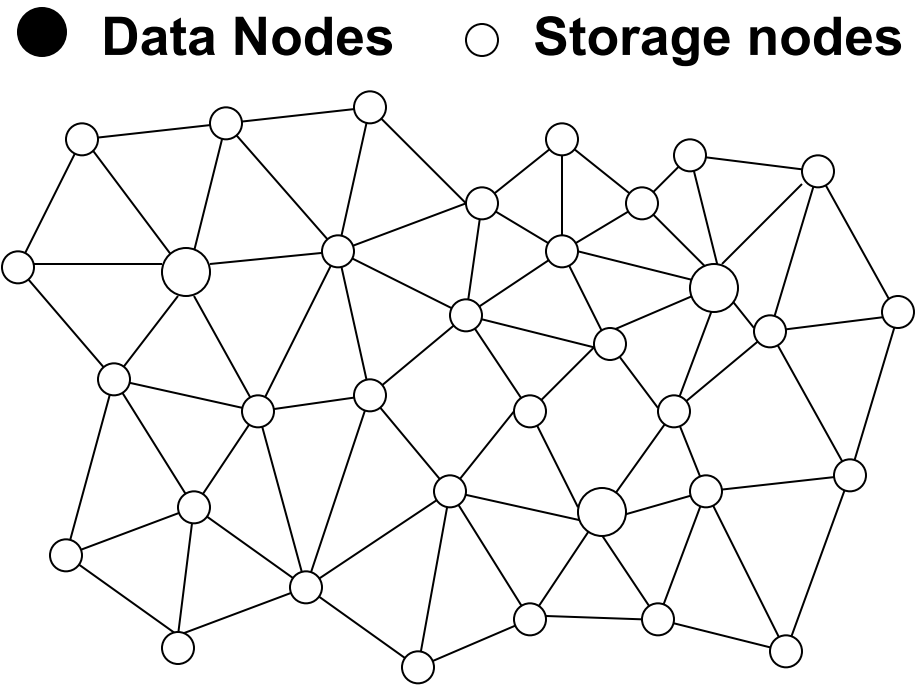
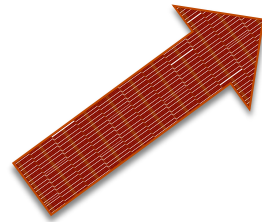
  - ❖ Available storage spaces

- ❖ **Data preservation**: offload overflow data from data node to storage nodes



# Overall Storage Overflow In Data Preservation

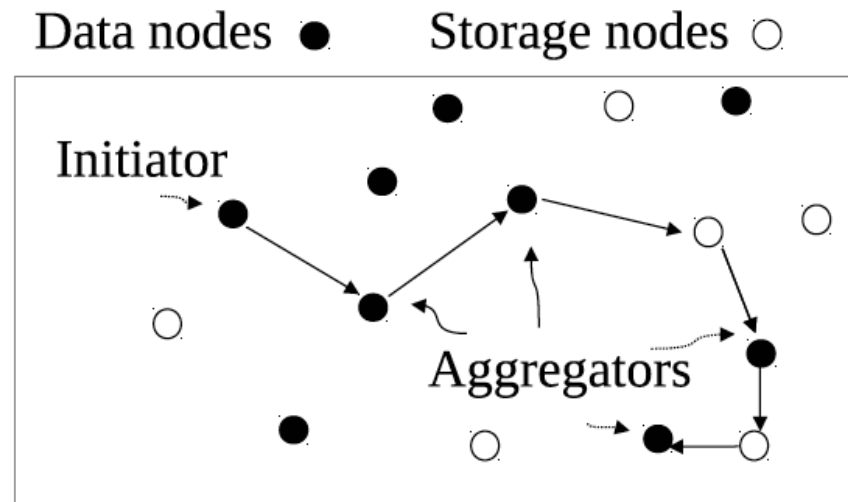
❖ When total size of overflow data exceeds the total available storage in the network



Overall storage overflow

# Solution - DAO<sup>2</sup> (Data Aggregation for Overall Storage Overflow)

- ❖ Spatial correlation among sensory data
- ❖ Two stages: 1) data aggregation, 2) data offloading



- ❖ Challenge: energy efficient data aggregation

# Problem Formulation of DAO<sup>2</sup>

- ❖ Undirected weighted graph  $G(V, E)$
- ❖  $p$  data nodes, each has  $R$  bits of overflow data
  - ❖ when a data node receives data information from at least another data node, it becomes an aggregator, and
  - ❖ it reduces the size of its overflow data from  $R$  to  $r$ ,  $0 \leq r < R$
- ❖  $|V| - p$  storage nodes, each has  $m$  bits of storage space
- ❖ Due to overall storage overflow:  $p \times R > (|V| - p) \times m$

$$\frac{|V|m}{m+R} < p \leq \lfloor \frac{|V|m - R + r}{m+r} \rfloor$$

# Problem Formulation of DAO<sup>2</sup>

❖  $q$ : number of aggregators,

$$q = \left\lceil \frac{p \times (R + m) - |V| \times m}{R - r} \right\rceil$$

❖ Therefore, at most  $p-q$  sensor nodes can be initiators

❖ Energy model -  $u$  sends  $R$ -bit data to  $v$  over  $l_{u,v}$


$$E_t(R, l_{u,v}) = E_{elec} \times R + \epsilon_{amp} \times R \times l_{u,v}^2$$

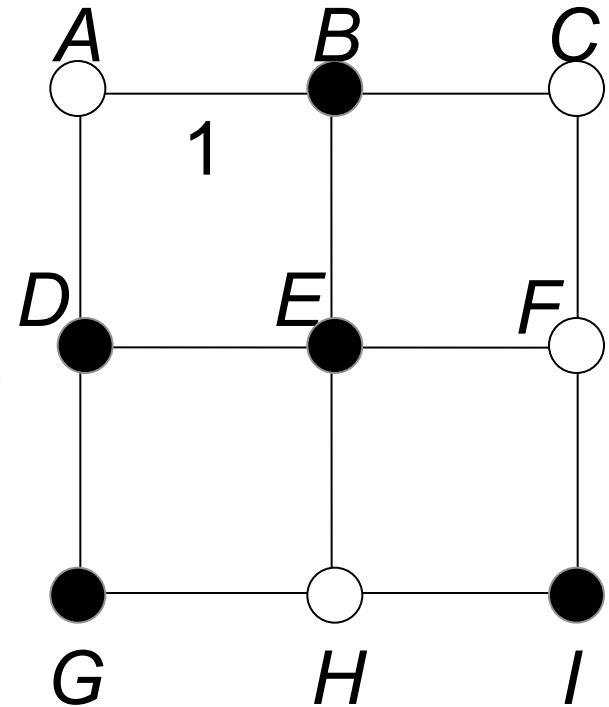
$$E_r(R) = E_{elec} \times R$$

❖ **Goal:** select a set of  $b$  ( $1 \leq b \leq p-q$ ) initiators, each visiting some data nodes (aggregators) following a walk, *s.t.* total  $q$  distinct aggregators are visited with minimum total energy cost

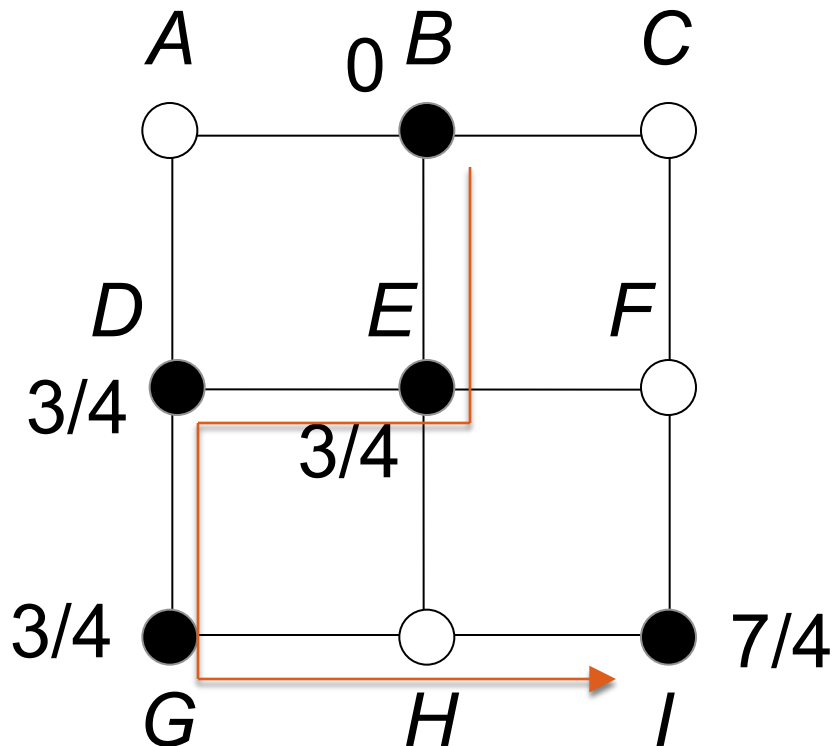


# An Example of DAO<sup>2</sup>

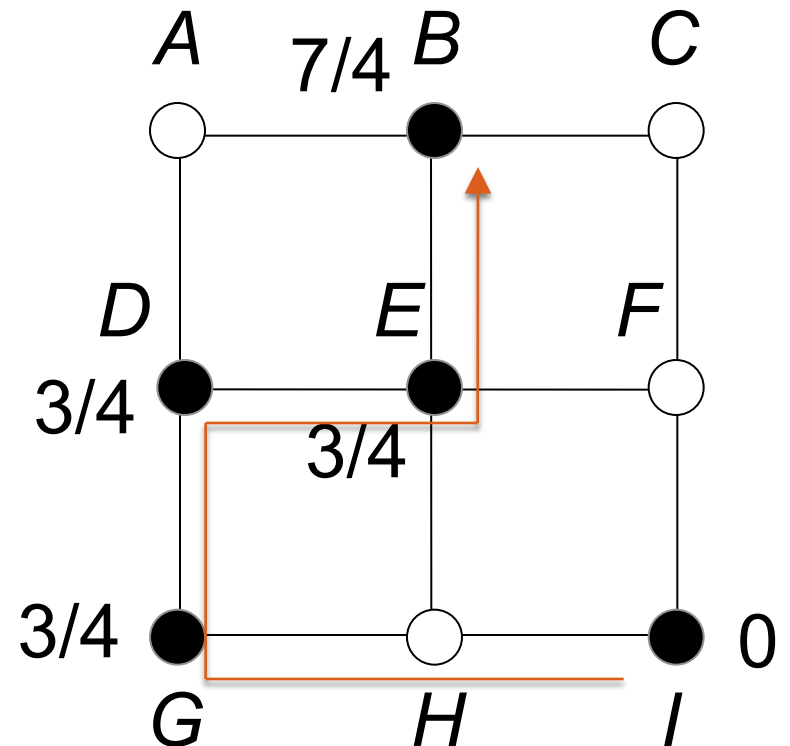
- ❖ Data nodes:  $B, D, E, G, I$
- ❖ Storage nodes:  $A, C, F, H$
- ❖  $R = m = 1$   overall storage overflow!
- ❖  $r = 3/4$ , number of aggregators  $q = 4$ , leaving one data node to be initiator
- ❖ Edge weight = 1
- ❖ Decide: which data node to be initiator and which path it visits?



# Two Optimal Solutions: cost=5

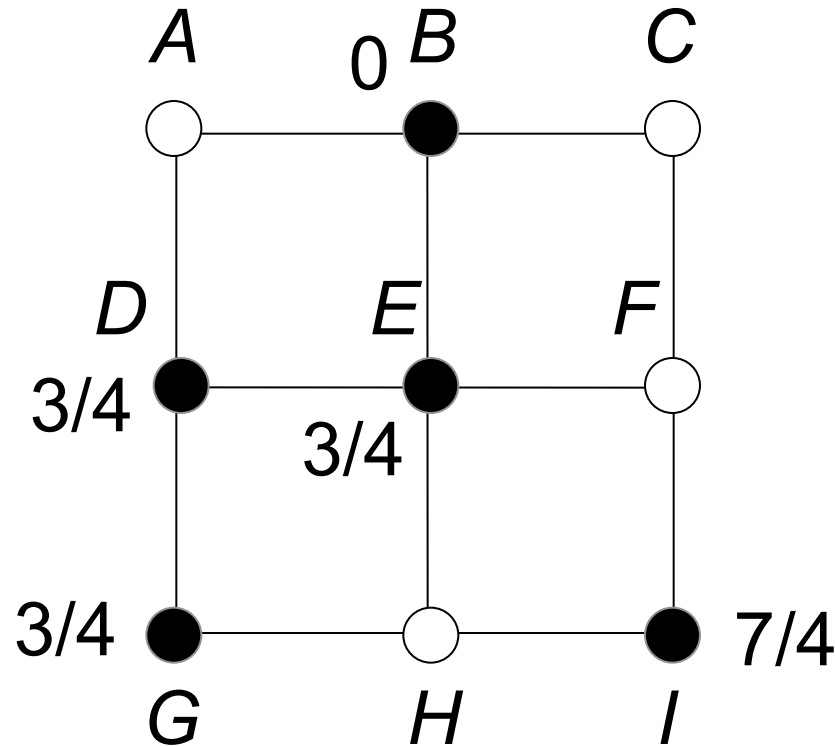


(a) B is initiator



(b) I is initiator

# Next, data offloading...



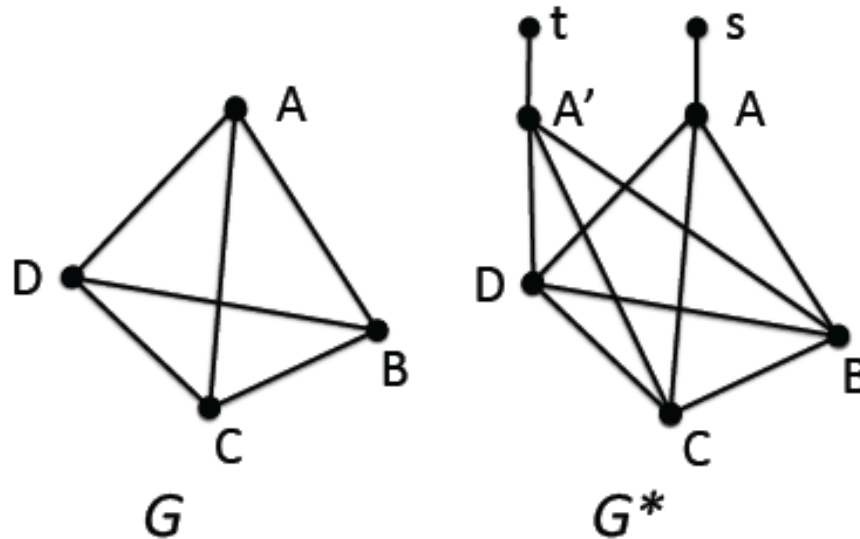
Equivalent to minimum cost flow problem  
(Tang et al. TOSN 2013)

# Multiple Traveling Salesman Walks (MTSW)

- ❖ **Input:** An undirected weighted graph  $G(V,E)$  and a number  $q$
- ❖ **Output:** Finds at most  $|V| - q$  **starting nodes**, each visiting some other nodes following a walk, *s.t.*
- ❖ **Goal:** total  $q$  nodes are visited while the total cost of the walks is minimized

# MTSW is NP-hard

- ❖ Traveling salesman path problem (TSPP) is a special case of MTSW, with  $q = |V| - 1$
- ❖ Prove TSPP is NP-hard, reduced from traveling salesman problem (TSP)



# Approximation Algo. for MTSW

**Algorithm 1:** Approximation Algorithm for MTSW.

**Input:**  $G(V, E)$  and number of nodes to visit  $q$ ;

**Output:**  $a$  walks:  $W_1, W_2, \dots, W_a$ , and  $\sum_{1 \leq j \in a} c(W_j)$ ;

0. **Notations:**

$E_q$ : set of  $q$  cycleless edges;

$G[E_q]$ : a  $q$ -edge forest;

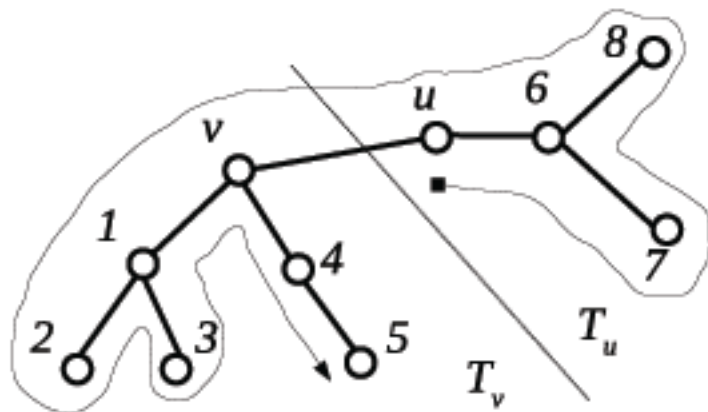
$C(G[E_q])$ : set of connected components in  $G[E_q]$ ;

$C_j$ : the  $j^{\text{th}}$  connected component in  $C(G[E_q])$ ;

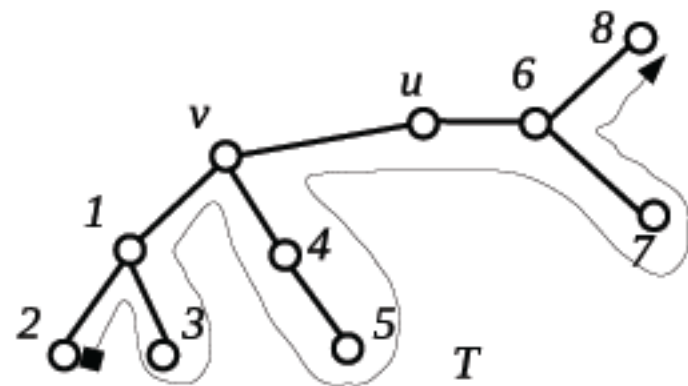
1. Let  $w(e_1) \leq w(e_2) \leq \dots \leq w(e_{|E|})$ ;
2.  $E_q = \phi$  (empty set),  $i = j = k = 1$ ;
3. **while** ( $k \leq q$ )
4.     **if** ( $e_i$  is a cycleless edge w.r.t.  $E_q$ )
5.          $E_q = E_q \cup \{e_i\}$ ;
6.          $k++$ ;
7.     **end if**;
8.      $i++$ ;
9. **end while**;
10. Let  $|C(G[E_q])| = a$ ; /\* $a$  connected components\*/
11. **for** ( $1 \leq j \leq a$ )
12.     **if** ( $C_j$  is linear) Start from one end node of  $C_j$  and visit the rest nodes in  $C_j$  once;
13.     **if** ( $C_j$  is a tree) Do a B-walk on  $C_j$ ;
14.     Let the resulted walk (or path) be  $W_j$ ;
15. **end for**;
16. **RETURN**  $W_1, W_2, \dots, W_a$ , and  $\sum_{1 \leq j \in a} c(W_j)$ .

- ❖ Find the  $q$  smallest cycleless edges, referred to as  $q$ -edge forest
- ❖ Traverse each tree in the forest using a B-walk
- ❖ Works alike and generalizes Kruskal's MST algo.
- ❖  $O(|E| \log |E|)$

# Binary Walk (B-Walk) and Longest-Path Walk (LP-Walk)



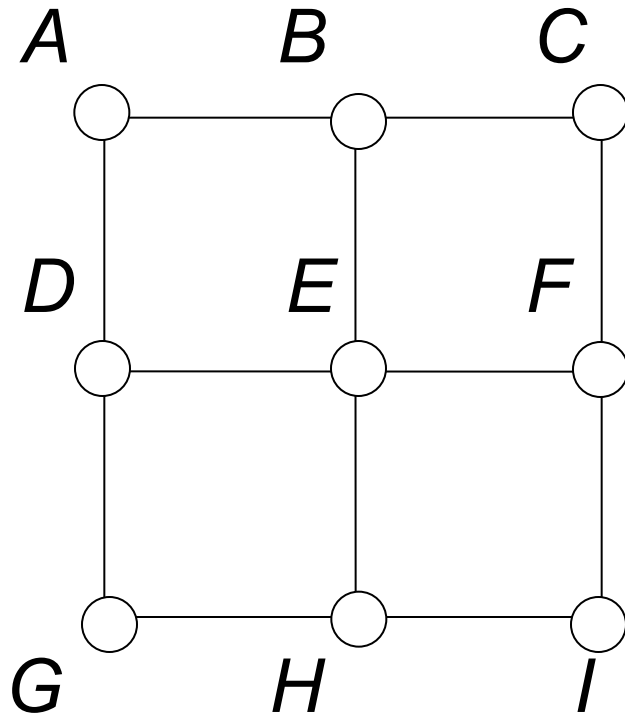
(a) B-Walk.



(b) LP-Walk.

$$c(W) \leq \left(2 - \frac{1}{|T|}\right) \times c(T)$$

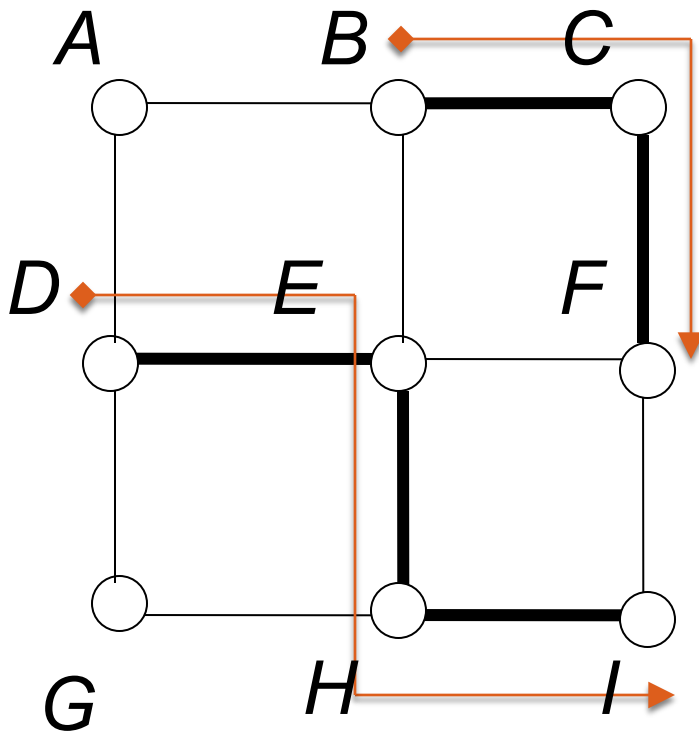
# An Example of Algo. 1 ( $q=5$ )



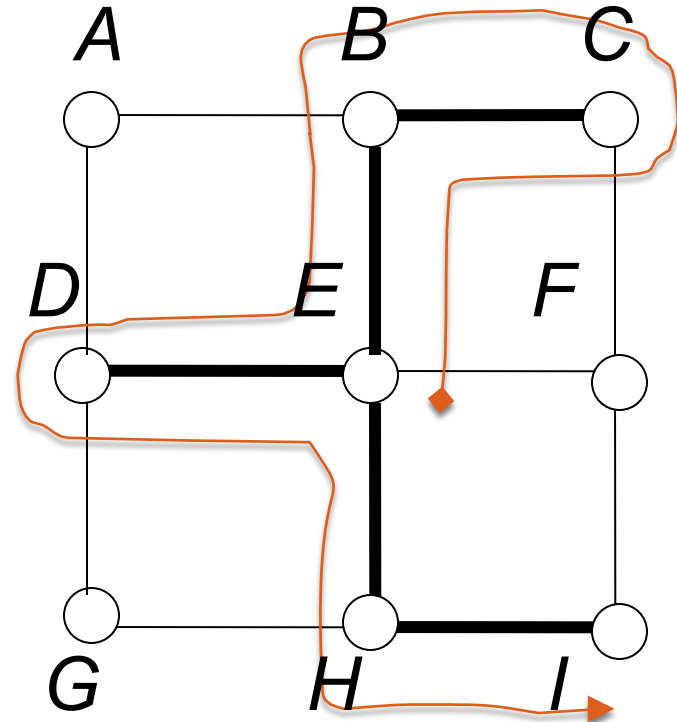
- ❖ Edge weight = 1
- ❖ How to visit 5 nodes energy efficiently?



# Many solutions...



- B, D are starting nodes
- C, F, E, H, I are visited
- Cost = 5



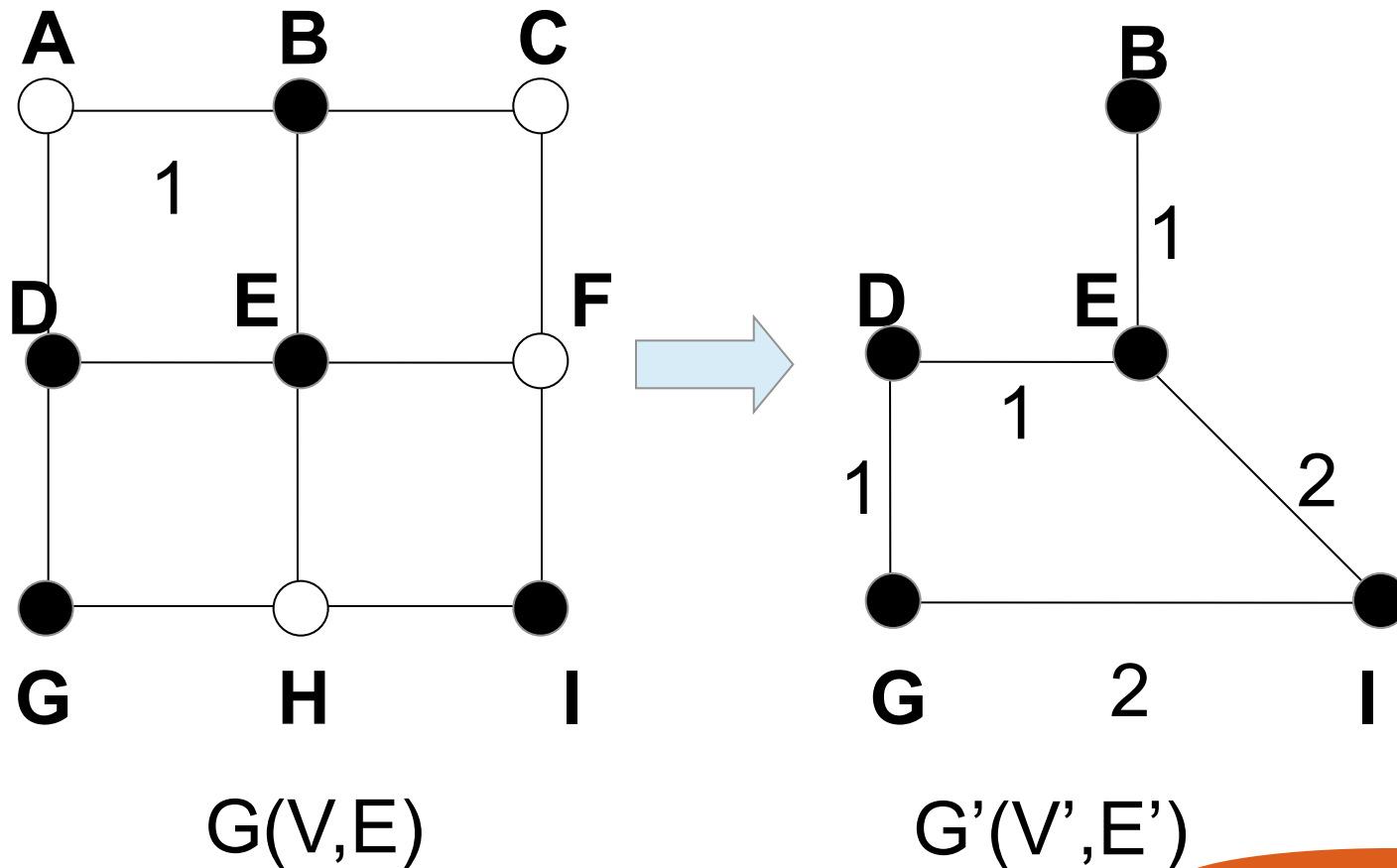
- E is starting node
- B, C, D, H, I are visited
- Cost = 8

# Analysis of Algo. 1

- ❖ Lemma 1: Its resulted  $q$ -edge forest is a **minimum  $q$ -edge forest**
- ❖ Lemma 2: The cost of the minimum  $q$ -edge forest is a lower bound of the optimal MTSW cost
- ❖ Theorem: Algorithm 1 is a  $(2 - 1/q)$  approximation algorithm

# Equivalency b/t MTSW and DAO<sup>2</sup>

**Theorem:** DAO<sup>2</sup> in sensor network  $G(V,E)$  is equivalent to MTSW in **aggregation network**  $G'(V',E')$



# Distributed DAO<sup>2</sup> Algorithm

Based on distributed minimum spanning tree algorithm by Gallager, Humblet, and Spira

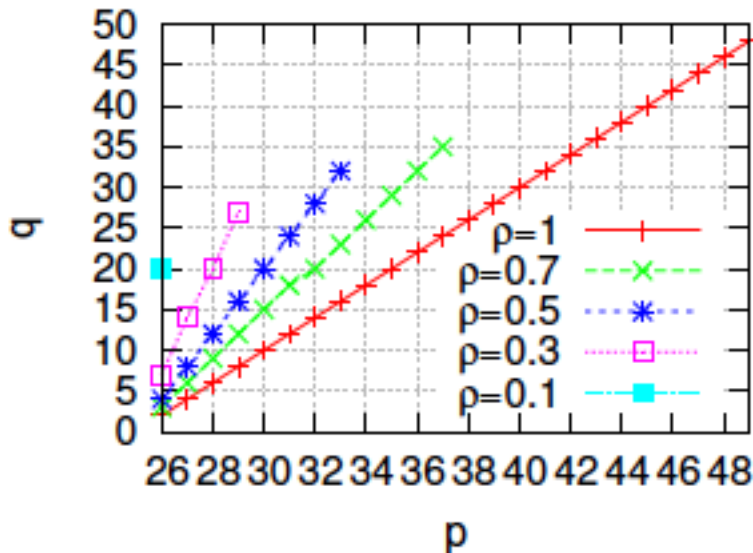
1. Starts with each node being considered as a fragment, with level value 0
2. Each level 0 node
  - 1) Chooses its minimum-weight incident edge and mark that edge as a **branch edge**.
  - 2) Sends a message via the branch edge to notify the node on the other side.
  - 3) Waits for a message from the other end of the edge.
3. The edge chosen by both nodes it connects becomes the core with level 1.
4. For a non-zero level fragment, the execution takes three stages: **broadcast, convergecast, and change core**
5. **while** (number of branch edges < q)
  - 1) Each fragment finds its minimum weight outgoing edge
  - 2) Uses it to combine with other fragments, using two operations: merge and absorb**end while**

It runs in  $O(N \log N)$  time and uses  $O(N \log N + E)$  messages.

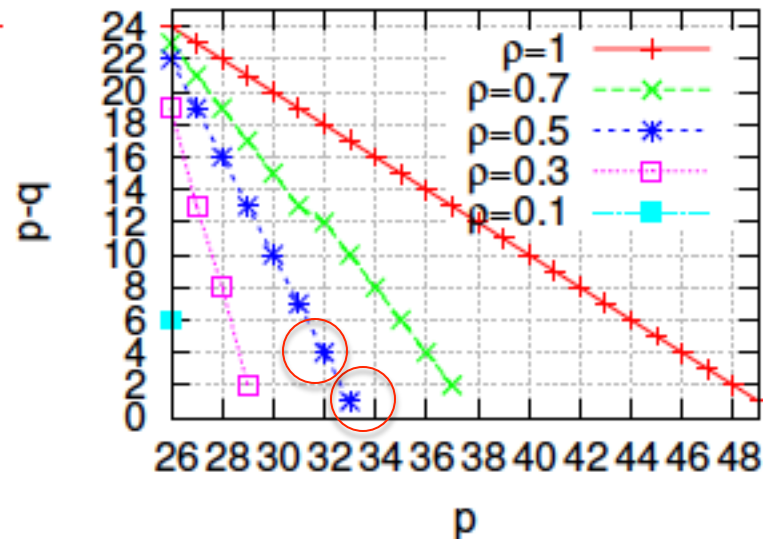
# Performance Evaluation

## ❖ Visual Performance Comparison

- ❖ 50 nodes in  $1000\text{m} \times 1000\text{m}$  network,  $T_r = 250\text{m}$
- ❖  $R = m = 512\text{MB}$ ,  $\rho = 1 - r/R$



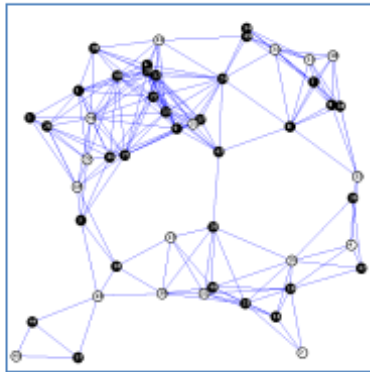
(a)  $q$  vs.  $p$ .



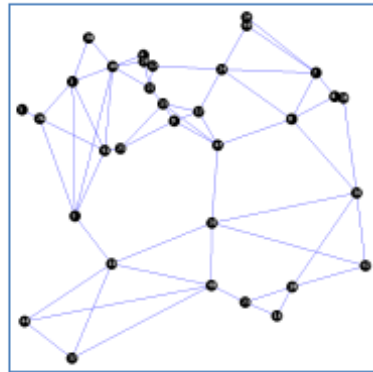
(b)  $p - q$  vs.  $p$ .

Fig. 6. Valid range of  $p$  while varying  $\rho$  ( $R = m$ ).

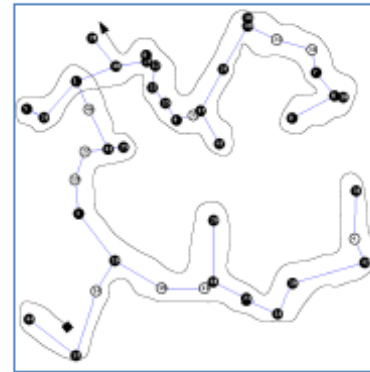




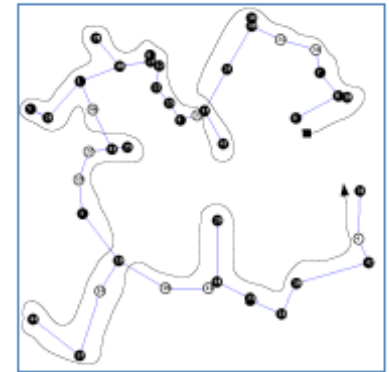
(a) Sensor network graph.



(b) Aggregation graph.

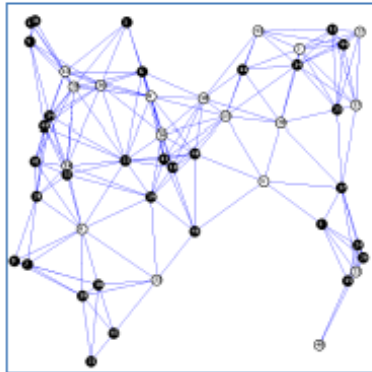


(c) B-Walk (cost=381.2J).

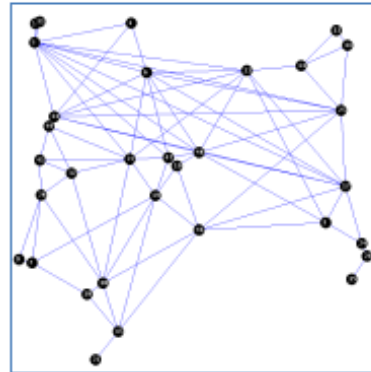


(d) LP-Walk (cost=290.6J).

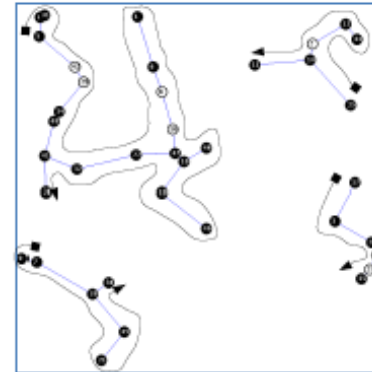
## One initiator



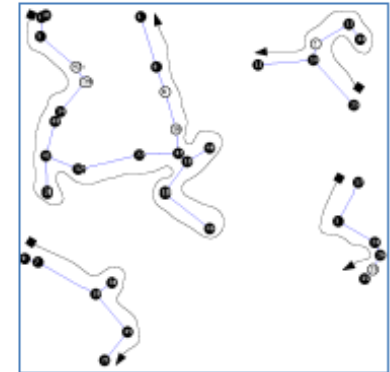
(a) Sensor network graph.



(b) Aggregation graph.



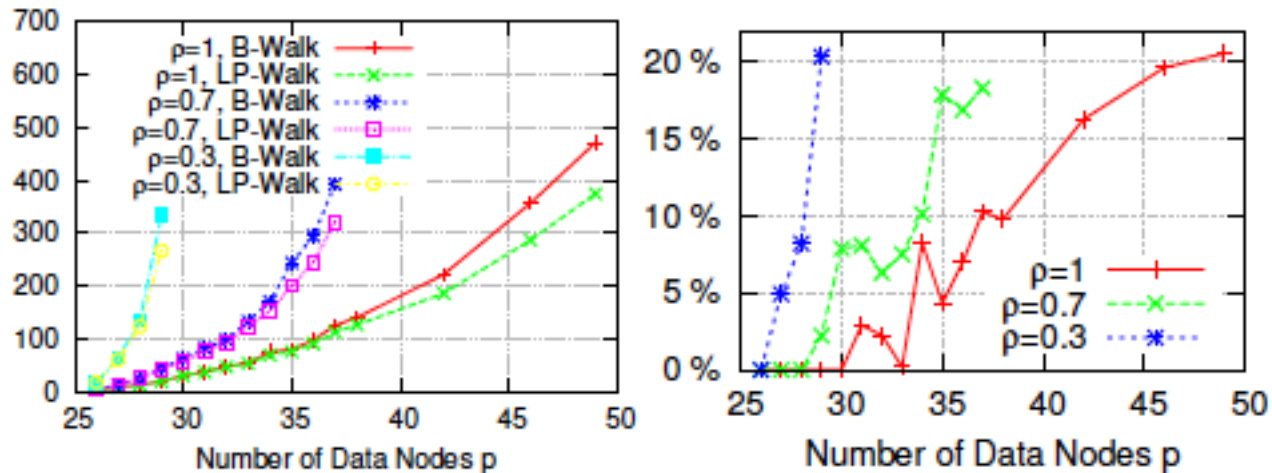
(c) B-Walk (cost=255.9J).



(d) LP-Walk (cost=203.0J).

## Four initiators

# Comparing B-Walk and LP-Walk



(a) Total aggregation cost (KJ).

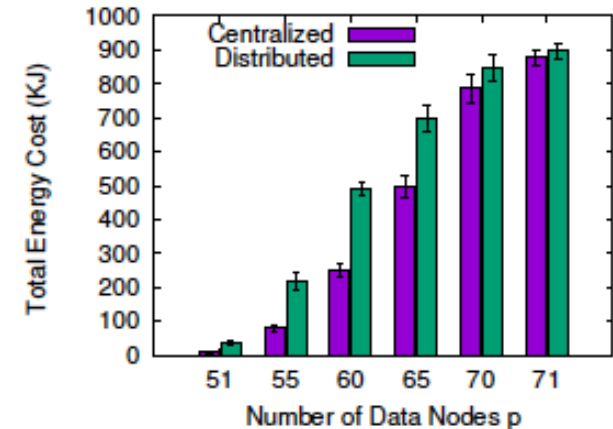
(b) Performance improvement.

Fig. 9. Comparing B-Walk with LP-Walk by varying  $p$  and  $\rho$ .

# Distributed DAO<sup>2</sup> Algorithm

$p$	55	60	65	70	71
$q$	17	34	50	67	70
Number of Initiators	38	26	15	3	1
Centralized (KJ)	78.79	251.76	494.12	787.07	876.29
Distributed (KJ)	209.52	479.12	680.93	827.76	876.29

TABLE II  
AGGREGATION COSTS IN CENTRALIZED AND DISTRIBUTED  
ALGORITHMS.



- ❖ Implemented in DistAlgo (Liu et al. OOPSLA 2012)
- ❖ 100 nodes in 2000m×2000m sensor network,  $T_r = 250m$
- ❖  $R=m=512MB$ , overhead message = 20B



# Conclusions and Future Works

- ❖ DAO<sup>2</sup> is an architectural and algorithmic framework to tackle overall storage overflow
- ❖ A new multiple traveling salesman walk problem
- ❖ Energy-efficient optimal, approximation, heuristic, and distributed algorithm
- ❖ Techniques applicable for any application where data correlation and resource constraints coexist
- ❖ Varying overflow data size and storage capacity
- ❖ Integrate data aggregation and data offloading