

DATA RESILIENCE VIA DATA AGGREGATION: OVERCOMING OVERALL STORAGE OVERFLOW IN SENSOR NETWORKS

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CONTENT

- ▶ Introduction
- ▶ Data overflow
- ▶ Data aggregation
- ▶ Formulation of Data Resilience via Data Aggregation (DRA)
- ▶ Multiple Traveling Salesman Walk Problem (MTSW)
- ▶ Solving DRA

INTRODUCTION

- ▶ Large amount of data
- ▶ Limited storage capacity
- ▶ Not feasible to install base station due to the challenging environment sensors are deployed in

DATA OVERFLOW

Data node : nodes with overflow data

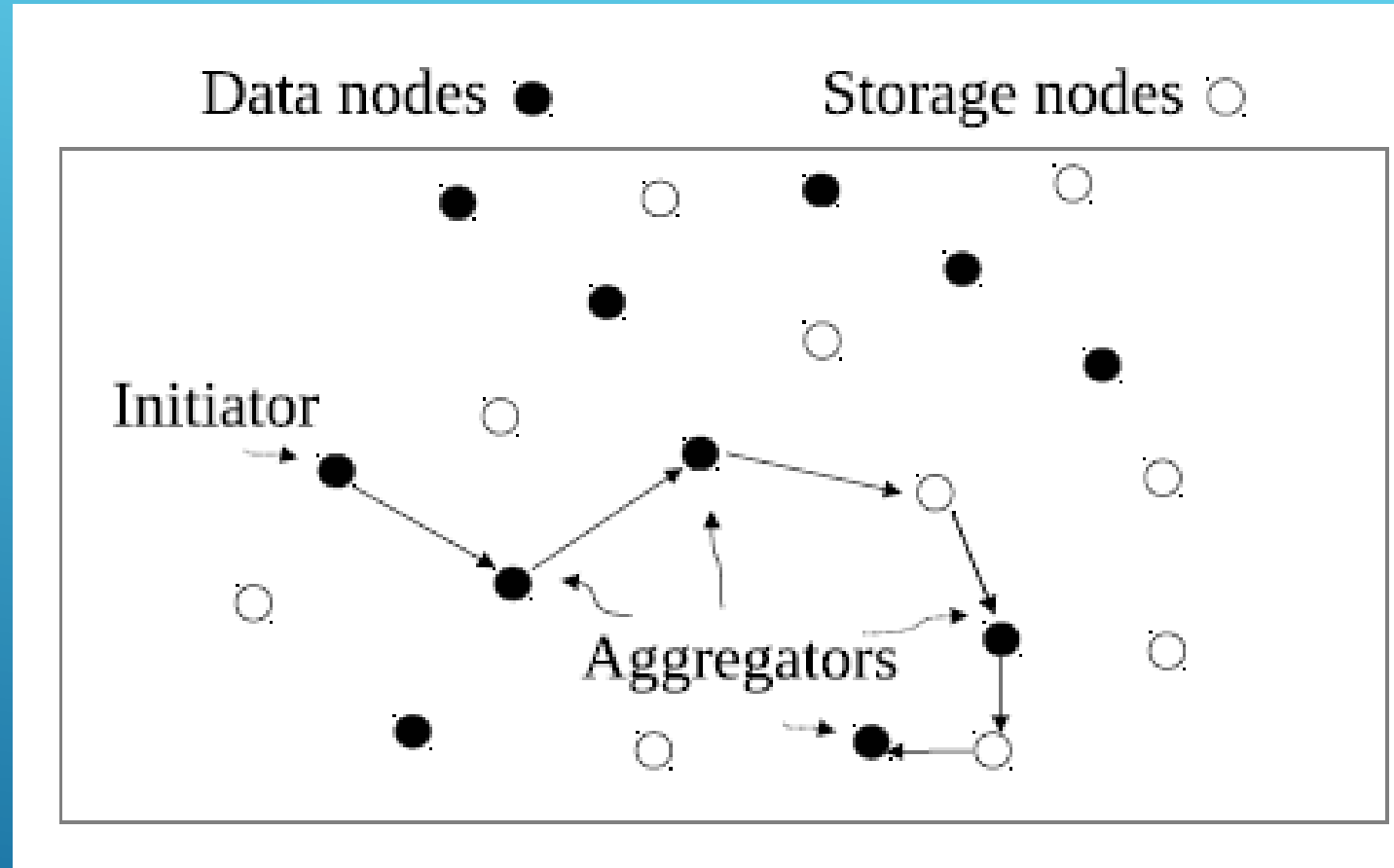
Storage nodes: nodes with available storage

- ▶ Node storage overflow
- ▶ Overall storage overflow

DATA AGGREGATION

Initiator : Send the overflow data to other nodes

Aggregator: receives the overflow data and aggregates its own overflow data



FORMULATION OF DRA

$$q = \lceil \frac{p \times (R + m) - |V| \times m}{R - r} \rceil$$

- ▶ q : the number of aggregators needed
- ▶ $|V|$: deployed sensor nodes
- ▶ m : the available storage space
- ▶ p : the number of data nodes
- ▶ R : the overflow data size at each data node before aggregation
- ▶ r : the overflow data size at each aggregator after aggregation

- ▶ At most $(p-q)$ can be selected as initiators
- ▶ The number of aggregation walks cannot exceed the number of initiators

EXAMPLE

Sensor network of 9 nodes:

Data Nodes: B D E G I

Storage Nodes: A C F H

$R = m = 1$

$r = \frac{3}{4}$

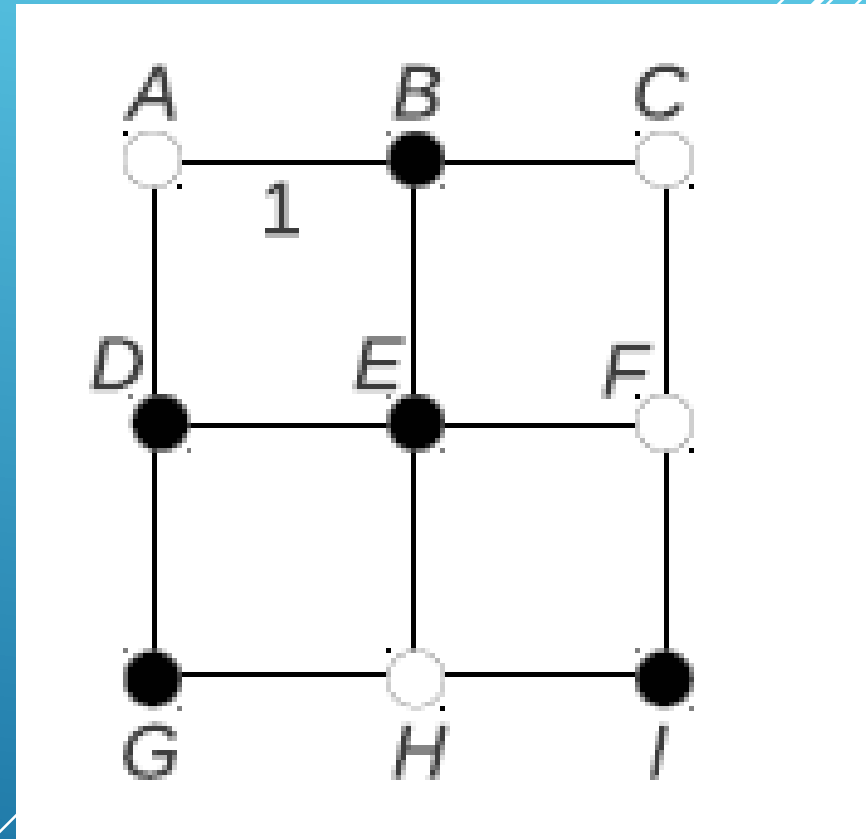
Energy consumption along any edge = 1

$q=4$ which means we have one initiator

Optimal Solution: B is the initiator

The walk is: B E D G H I

Cost : 5



OBJECTIVE OF MTSW

solving DRA in a sensor network is equivalent to solving MTSW in an aggregation graph transformed from sensor network.

- ▶ Given an undirected weighted graph $G = (V;E)$ with $|V|$ nodes and $|E|$ edges
- ▶ a cost metric (which represents the distance or traveling time between two nodes)
- ▶ MTSW determine a subset of at most b starting nodes (i.e., the initiator in DRA)

salesman can be dispatched to visit a number of other nodes

following a walk, such that

- a) all together q nodes (excluding starting nodes) are visited
- b) the total cost of the walks is minimized

MTSW DECIDE

Set of starting nodes

Set of walks

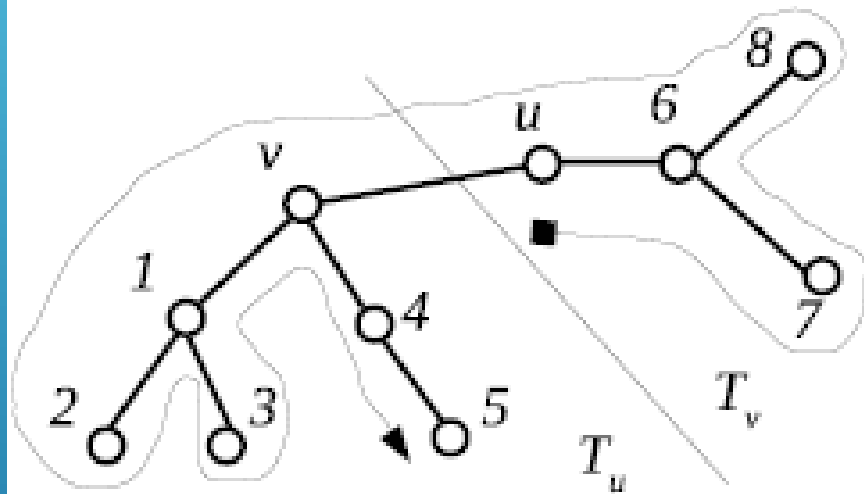
Such that

Walking cost is minimized

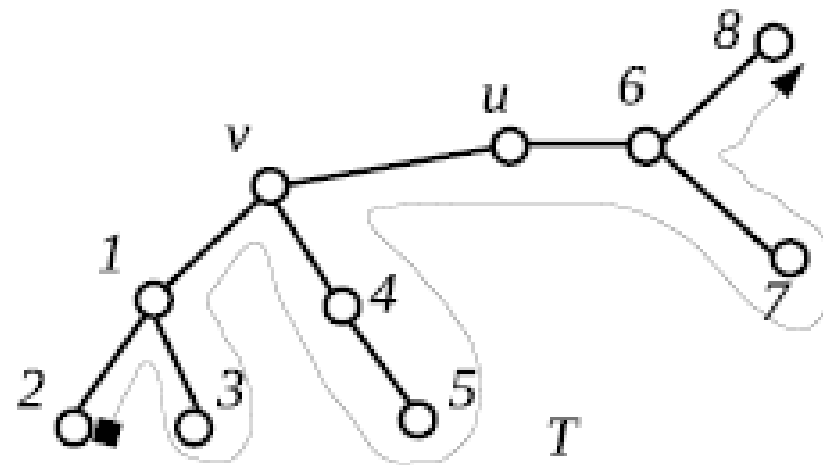
ALGORITHMIC SOLUTION OF MTSW (SOLVING DRA)

- ▶ Approximation Algorithm
 - ❖ B walk
- ▶ Heuristic algorithm
 - ❖ LP walk

We need better energy consumption (lower walk cost)



(a) B-Walk.



(b) LP-Walk.

THE APPROXIMATION ALGORITHM

yields a total cost of the walks that is at most $(2 - 1/q)$ times of the optimal cost.

1- sorts all the edges in E into nondecreasing order of their weights

2- initializes the set E_q to the empty set and creates $|V|$ trees, each containing one node

3- checks each edge, if it is cycleless w.r.t. E_q . If yes, add it into E_q

4- repeat 3 until we have q edges

It then obtains:

all the connected components induced by these q edges.

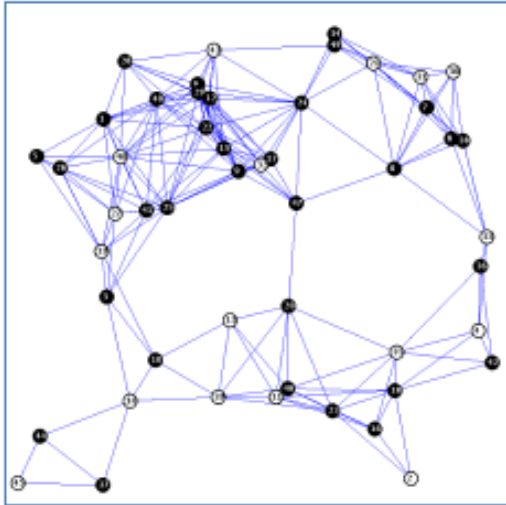
If linear topology : start from one end visits the nodes in the linear topology exactly once

If it is a tree : B walk along the tree

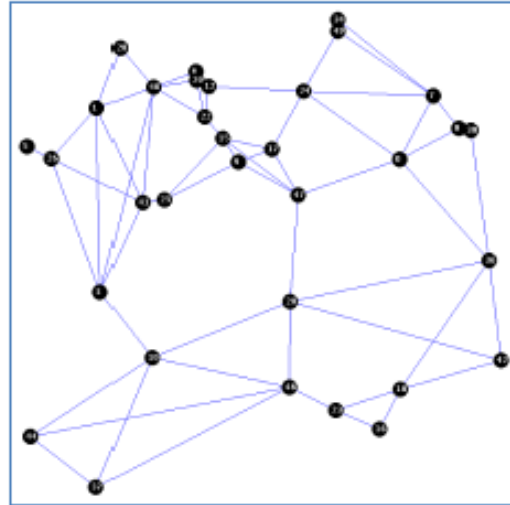
HEURISTIC ALGORITHM

- ▶ Improve the performance of the approximation algorithm by using LP walk instead of the B walk

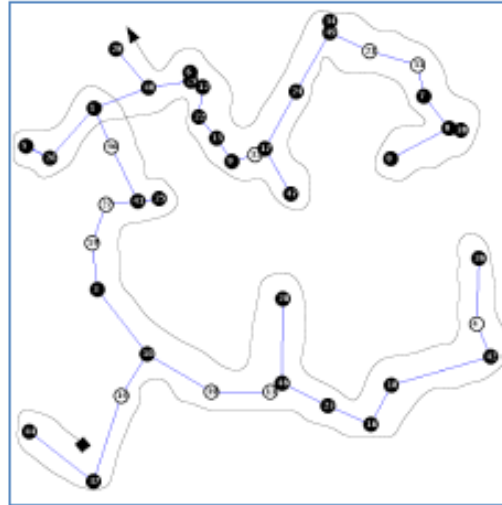
COMPARISON



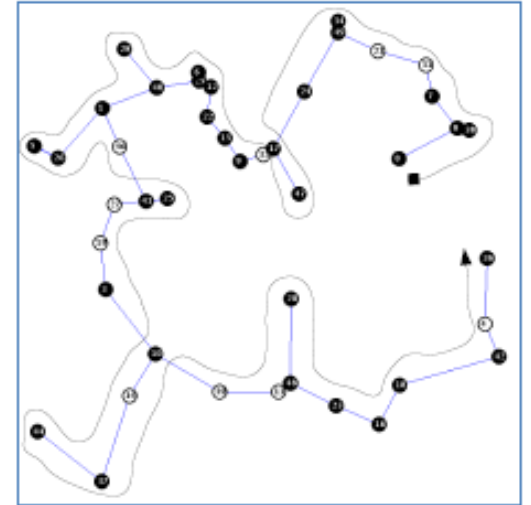
(a) Sensor network graph.



(b) Aggregation graph.



(c) B-Walk (cost=381.2J).



(d) LP-Walk (cost=290.6J).

THANK YOU