

Copyrighted material - for classroom use only

Note Title

5/7/2013

NP-Complete Problems

Only for CSC501 & CSC401 at CSUDH

P* and *NP

***NP*-Complete Problems**

Approximation Algorithms

Bin Packing

**The Knapsack and Subset Sum
Problems**

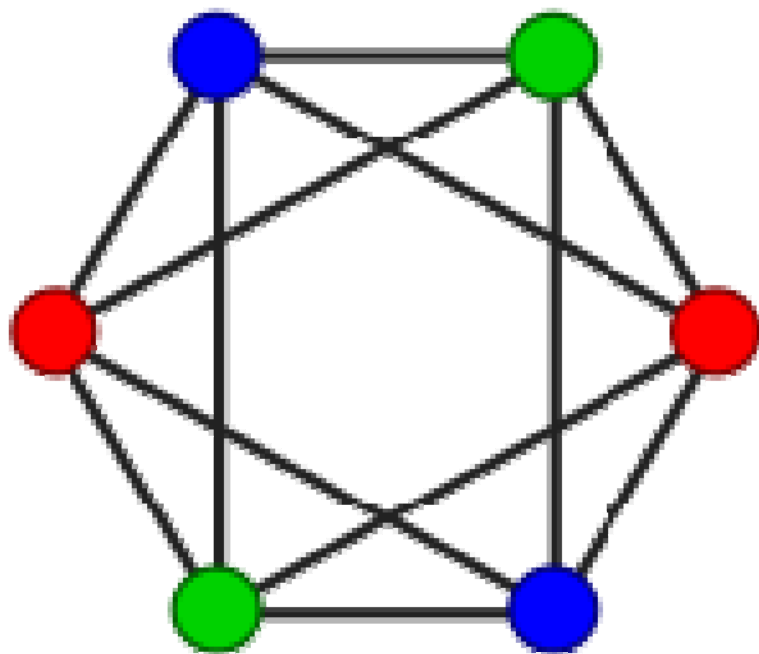
Graph Coloring

Graph Coloring

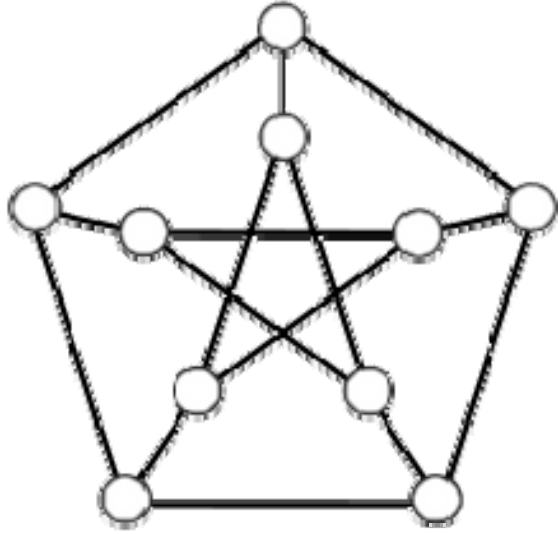
A *coloring* of a graph $G = (V, E)$ is a mapping $C:V \rightarrow S$, where S is a finite set (of “colors”), such that if $vw \in E$ then $C(v) \neq C(w)$; in other words, adjacent vertices are not assigned the same color. The *chromatic number* of G , denoted $\chi(G)$, is the smallest number of colors needed to color G , that is, the smallest k such that there exists a coloring C for G and $|C(V)| = k$.

Optimization problem: Given G , determine $\chi(G)$ (and produce an optimal coloring, i.e., one that uses only $\chi(G)$ colors).

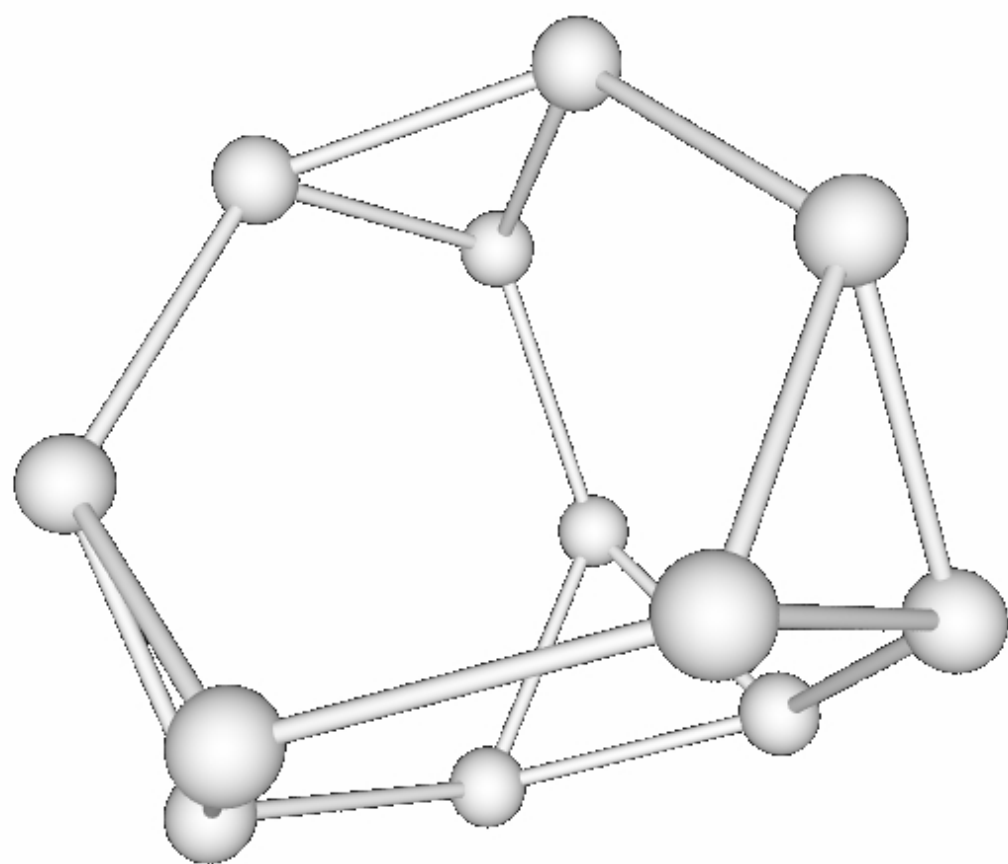
Decision problem: Given G and a positive integer k , is there is a coloring of G using at most k colors? (If so, G is said to be *k-colorable*.)



An example of graph
that is 3-colorable
but not 2-colorable



Another example



Job Scheduling with Penalties

Suppose that n jobs J_1, \dots, J_n are to be executed one at a time. We are given execution times t_1, \dots, t_n , deadlines d_1, \dots, d_n (measured from the starting time for the first job executed), and penalties for missing the deadlines p_1, \dots, p_n . Assume that the execution times, deadlines, and penalties are all positive integers. A schedule for the jobs is a permutation π of $\{1, 2, \dots, n\}$, where $J_{\pi(1)}$ is the job done first, $J_{\pi(2)}$ is the job done next, and so forth. The total penalty for a particular schedule is

$$P_\pi = \sum_{j=1}^n \left[\text{if } t_{\pi(1)} + \dots + t_{\pi(j)} > d_{\pi(j)} \text{ then } p_{\pi(j)} \text{ else } 0 \right].$$

Optimization problem: Determine the minimum possible penalty (and find an optimal schedule, i.e., one that minimizes the total penalty).

Decision problem: Given, in addition to the inputs described, a nonnegative integer k , is there a schedule with $P_{\pi} \leq k$?

Bin Packing

Suppose we have an unlimited number of bins each of capacity 1, and n objects with sizes s_1, \dots, s_n , where $0 < s_i \leq 1$.

Optimization problem: Determine the smallest number of bins into which the objects can be packed (and find an optimal packing).

Decision problem: Given, in addition to the inputs described, an integer k , do the objects fit in k bins?

Knapsack

Suppose we have a knapsack of capacity C (a positive integer) and n objects with sizes s_1, \dots, s_n and “profits” p_1, \dots, p_n (where s_1, \dots, s_n and p_1, \dots, p_n are positive integers).

Optimization problem: Find the largest total profit of any subset of the objects that fits in the knapsack (and find a subset that achieves the maximum profit).

Decision problem: Given k , is there a subset of the objects that fits in the knapsack and has a total profit at least k ?

Subset Sum

The input is a positive integer C and n objects whose sizes are positive integers s_1, \dots, s_n .

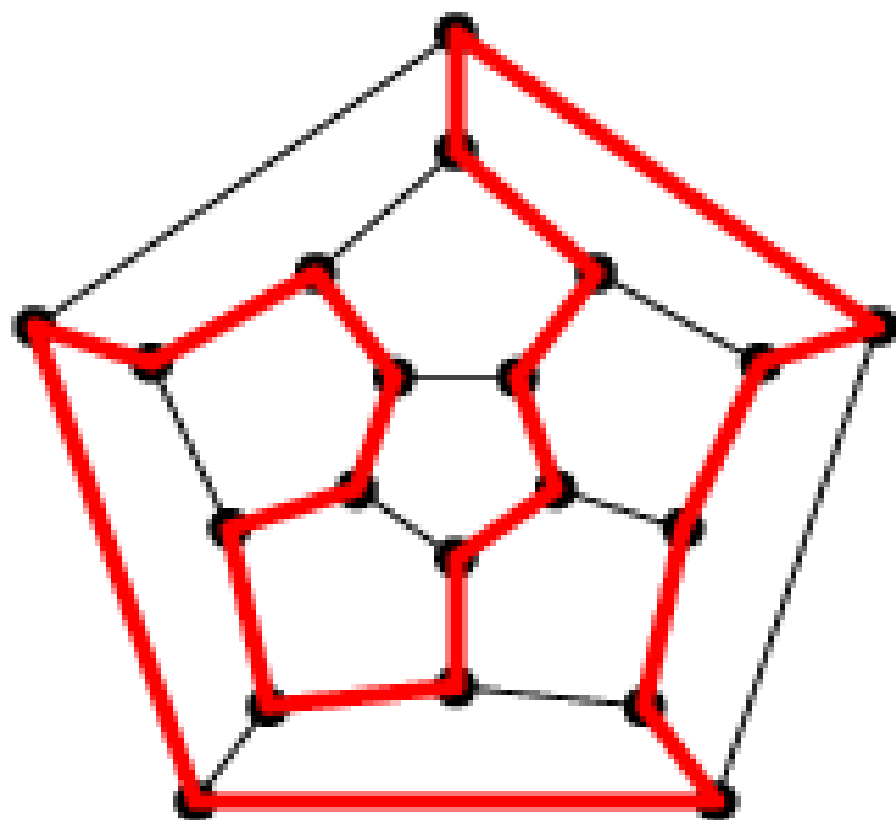
Optimization problem: Among subsets of the objects with sum at most C , what is the largest subset sum?

Decision problem: Is there a subset of the objects whose sizes add up to exactly C ?

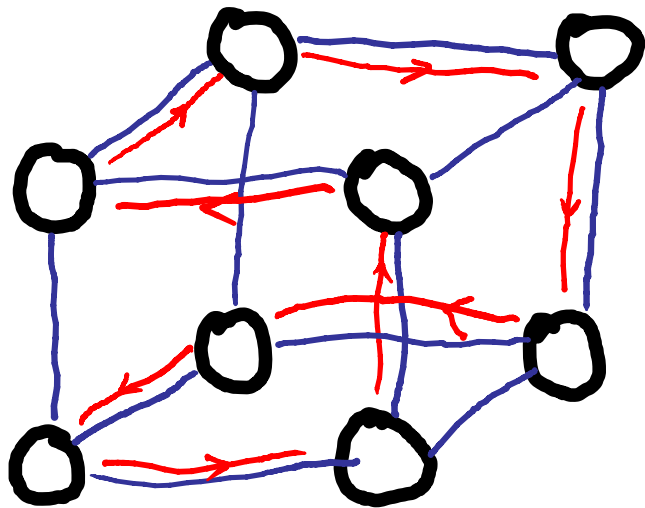
Hamilton Paths and Hamilton Circuits

A Hamilton path (Hamilton circuit, or cycle) in a graph or digraph is a path (cycle) that passes through every vertex exactly once. (*Circuit* is another term for *cycle*, and Hamilton cycles are most commonly called Hamilton circuits.)

Decision problem: Does a given graph or digraph have a Hamilton path (circuit)?



3 - cube



does have a
Hamiltonian cycle.

And so does any

n - cube

Minimum Tour (Traveling Salesman Problem)

Optimization Problem: Given a weighted graph, find a minimum weighted Hamilton circuit.

This problem is widely known as the traveling salesperson problem; the salesperson wants to minimize total traveling while visiting all the cities in a territory. Other applications include routing trucks for garbage pickup and package delivery.

Decision Problem: Given a weighted graph and an integer k , is there a Hamilton circuit with total weight at most k ?

CNF-satisfiability

A logical (or Boolean) variable is a variable that may be assigned the value *true* or *false*. If v is a logical variable, then \bar{v} , the negation of v , has the value *true* if and only if v has the value *false*. A *literal* is a logical variable or the negation of a logical variable. A *clause* is a sequence of literals separated by the Boolean or operator (\vee). A logical expression in *conjunctive normal form* (CNF) is a sequence of clauses separated by the Boolean and operator (\wedge). An example of a logical expression in CNF is

$$(p \vee q \vee s) \wedge (\bar{q} \vee r) \wedge (\bar{p} \vee r) \wedge (\bar{r} \vee s) \wedge (\bar{p} \vee \bar{s} \vee \bar{q}),$$

where p , q , r , and s are logical variables.

Decision problem: Is there a truth assignment, i.e., a way to assign the values *true* and *false*, for the variables in the expression so that the expression has value *true*?

Exercise

Is this CNF formula satisfiable?

$$(p \vee q \vee s) \wedge (\bar{q} \vee r) \wedge (\bar{p} \vee r) \wedge (\bar{r} \vee s) \wedge (\bar{p} \vee \bar{s} \vee \bar{q}) \wedge (q \vee \bar{s})$$

Answer this question in two ways.

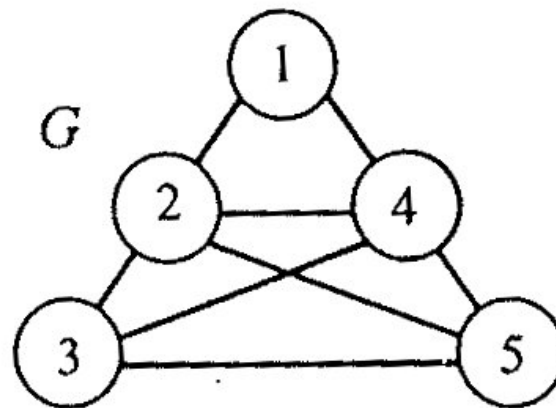
1. By brute force - try all truth assignments

2. By logic + brute force - first, simplify the formula using logic and then try truth assignments.

You should see that way 2 is faster than way 1.

Example 1 Nondeterministic graph coloring

Let $k = 4$ and let the graph G in Fig. 1 be the input. For simplicity, we will denote colors by letters B (blue), R (red), G (green), O (orange), and Y (yellow). (This is not a satisfactory notation in general because large graphs may need more than 26 colors.) Here is a list of a few possible strings s and the output that would result.



Input: 4, 5, (1,2) (1,4) (2,4) (2,3) (3,5) (2,5) (3,4) (4,5)

$\underbrace{\hspace{1.5cm}}$
 k number
of vertices

 $\underbrace{\hspace{10cm}}$
edges of G

Input for nondeterministic graph coloring

s	Output	Reason
RGRBG	<i>no</i>	v_2 and v_5 , both green, are adjacent
RGRB	<i>no</i>	Not all vertices are colored
RB YGO	<i>no</i>	More than k colors
RGRBY	<i>yes</i>	A valid 4-coloring
R%*,G@	<i>no</i>	Bad syntax

Since there is one possible computation of the algorithm that produces a *yes* output, the answer for the input G is *yes*.

The Class P

Definition P is the class of decision problems that are polynomial bounded.

$q \in P$ iff \exists program s that solves (or answers) q , and
 \exists constant k , such that:
 s solves problem q and the worst-case
running time t of s satisfies
 $t(n) \in O(n^k)$
where n is the size of an input to q (and s)

The Class **NP**

A *nondeterministic algorithm* has two phases:

1. The nondeterministic phase. Some completely arbitrary string of characters, s , is written beginning at some designated place in memory. Each time the algorithm is run, the string written may differ. (This string may be thought of as a guess at a solution for the problem, so this phase may be called the guessing phase, but s could just as well be gibberish.)
2. The deterministic phase. A deterministic (i.e., ordinary) algorithm begins execution. In addition to the decision problem's input, the algorithm may read s , or it may ignore s . Eventually it halts with an output of *yes* or *no* — or it may go into an infinite loop and never halt. (Think of this as the checking phase — the deterministic algorithm is checking s to see whether it is a solution for the decision problem's input.)

Non-deterministic algorithm (solution) $A(I)$ for a decision problem " $P(I)?$ "

1. Given an instance i of input I , "guess" string s .
2. Given an instance i of input I and s , determine if s is a witness of " $\text{The answer to } P(I)? \text{ is YES}$ ".
3. If step 2 (above) ended with the positive determination, output " YES " and stop. Otherwise, stop.

Extra condition not mentioned in the text.

4. For every valid instance i of the input I for the problem $P(I)$:

there exists a “guess” s for which $A(i)$ outputs "YES"

if, and only if,

"YES" is the correct answer to the instance " $P(i)$?" of the problem " $P(I)$ ".

Definition NP is the class of decision problems for which there is a polynomial-bounded nondeterministic algorithm. (The name NP comes from “nondeterministic polynomial bounded.”)

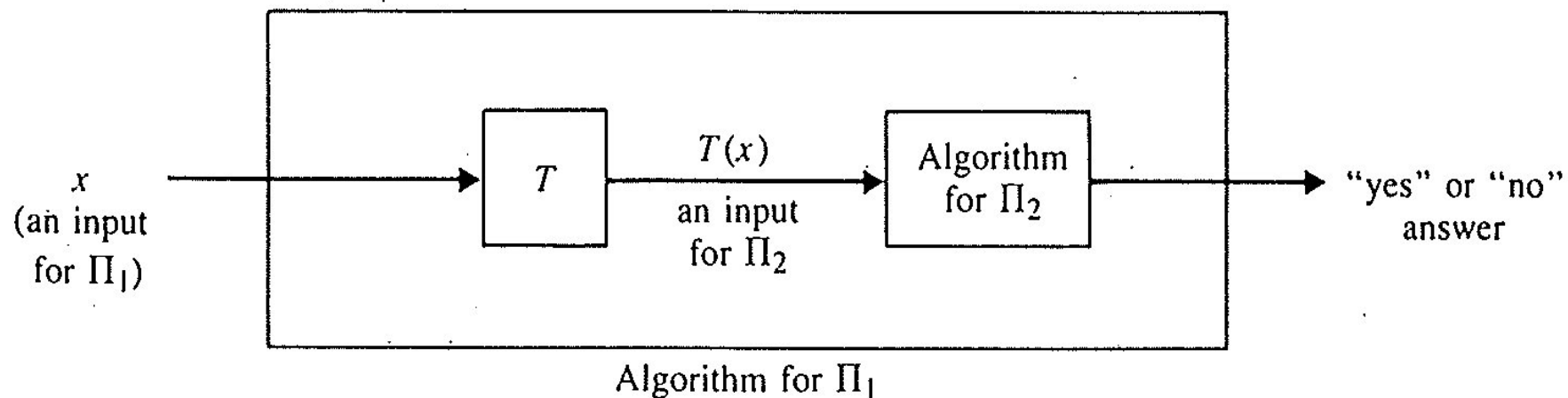
Theorem .1 Graph coloring, the Hamilton path and circuit problems, job scheduling with penalties, bin packing, the subset sum problem, the knapsack problem, CNF-satisfiability, and the traveling salesperson problem are all in NP .

Theorem .2 $P \subseteq NP$.

NP-Complete Problems

Notation: $\Pi_1 \leq \Pi_2$

Polynomial Reductions



Reduction of problem Π_1 to problem Π_2 . Π_2 's answer for $T(x)$ must be the same as Π_1 's answer for x .

Example A simple reduction

Let the problem Π_1 be: Given n Boolean variables, does at least one of them have the value *true*? (In other words, this is a decision-problem version of computing Boolean or.) Let Π_2 be: Given n integers, is the maximum of the integers positive? Let $T(x_1, x_2, \dots, x_n) = y_1, y_2, \dots, y_n$ where $y_i = 1$ if $x_i = \textit{true}$, and $y_i = 0$ if $x_i = \textit{false}$. Clearly an algorithm to solve Π_2 , when applied to y_1, y_2, \dots, y_n , solves Π_1 for x_1, x_2, \dots, x_n . ■

Definition Let T be a function from the input set for a decision problem Π_1 into the input set for a decision problem Π_2 . T is a *polynomial reduction* (also called a *polynomial transformation*) from Π_1 to Π_2 if

1. T can be computed in polynomial-bounded time, and
2. For every input x for Π_1 , the correct answer for Π_2 on $T(x)$ is the same as the correct answer for Π_1 on x .

Notation: $\Pi_1 \leq_p \Pi_2$

Definition Π_1 is *polynomially reducible* (also called *polynomially transformable*) to Π_2 if there exists a polynomial transformation from Π_1 to Π_2 . (We usually simply say that Π_1 is *reducible* to Π_2 ; the polynomial bound is understood.) The notation $\Pi_1 \leq_p \Pi_2$ is used to indicate that Π_1 is reducible to Π_2 .

Theorem .3 If $\Pi_1 \leq_p \Pi_2$ and Π_2 is in P , then Π_1 is in P .

Definition A problem Π is *NP-complete* if it is in NP and for every other problem Π' in NP , $\Pi' \leq_p \Pi$.

Theorem .4 If any *NP-complete* problem is in P , then $P = NP$.

Theorem 1.5 (Cook's theorem) The CNF-satisfiability problem is *NP*-complete.

Theorem 1.6 Graph coloring, the Hamilton path and circuit problems, job scheduling with penalties, bin packing, the subset sum problem, the knapsack problem, and the traveling salesperson problem are all *NP*-complete.

A problem that is not known to be in NP or P

Integer factorization problem.

Optimization. Given an integer $n > 1$, find prime factorization of n .

($n = k_1^{x_1} \times \dots \times k_m^{x_m}$, where k_i 's are prime and x_i 's are integer)

Decision problem. Given $k \geq 1$, does n have a factor larger than 1 and less than k ?

The integer factorization problem is not known to be in NP and is not known to be in P.

However, the primality problem (Is n a prime number?) has been proven to be in P.

AKS primality test has a worst-case polynomial time (size $n = \lfloor \lg n \rfloor + 1$).

hard

To show that the problem Π is ~~NP -complete~~, choose some known NP -complete problem Π' and reduce Π' to Π , not the other way around. The logic is as follows:

Since Π' is NP -complete, all problems in $NP \leq_P \Pi'$.

Show $\Pi' \leq_P \Pi$.

Then all problems in $NP \leq_P \Pi$.

Therefore, Π is ~~NP -complete~~.

hard

No one knows if $P = NP$.

Many top experts believe $P \neq NP$.

There are some results suggesting that it is extremely difficult to decide the question :

Is $P = NP$?

Example from our experience with math.

Some easy looking theorems (like Fermat's theorem saying that $x^n + y^n = z^n$ has integer solutions for $x > 0, y > 0, z > 0$ iff $n = 1$ or 2)
Proved really hard to prove. But once a proof has been published, everybody with enough math preparation can verify it.

If $P \neq NP$ then

There are solvable problems that are extremely difficult to solve, but once they are solved, checking their solution is easy. And so is distribution of that solution.

It's a bit like with password-protected computer.

As long as the password is kept secret, it is very difficult for a hacker to login.

Once a password is guessed, it becomes easy to login (and to distribute it).

If $P \neq NP$ then...

Job scheduling problem is practically unsolvable, except, perhaps, for some special (easy) cases.

This explains
(distributed)

outcomes for

economies.

why free-market
economies
centrally-planned

This also explains how knowledge workers can be deprived of the fruits of their work.

What Makes a Problem Hard?

The 3-CNF satisfiability problem is the CNF-satisfiability problem restricted to expressions with exactly three literals per clause. It is *NP*-complete. If there are at most two literals per clause, satisfiability can be checked in polynomial-bounded time.

A *k*-clique in a graph is a subgraph consisting of *k* mutually adjacent vertices (i.e., a complete graph on *k* vertices.)

The problem of determining whether a graph has a *k*-clique is *NP*-complete, but for planar graphs it is in *P* because a planar graph cannot have a clique with more than four vertices. (The clique problem is also in *P* for graphs with bounded degrees.)

Determining if a graph is 2-colorable is easy; determining if it is 3-colorable is *NP*-complete. It is still *NP*-complete if the graphs are planar and the maximum degree is 4.

These examples do not yield any nice generalizations about *why* a problem is *NP*-complete. There are still a great many open questions in this field, the main one being, of course, Does $P = NP$?

Determining an existence of Hamiltonian cycle in a graph G is hard. (But easy for: n -cube, complete graph, acyclic graph, etc.

Determining an existence of Euler's cycle (passes through every edge once and covers all vertices) in a graph G is easy.

Question: How to do that?