

**Upper bounds and lower bounds on
the time necessary to solve the problem,
with example FindMax**

(See page 39 - 40 of textbook for more narrative.)

Suppose that a problem $Q(I)$ has only three solutions whose worst-case running times are :

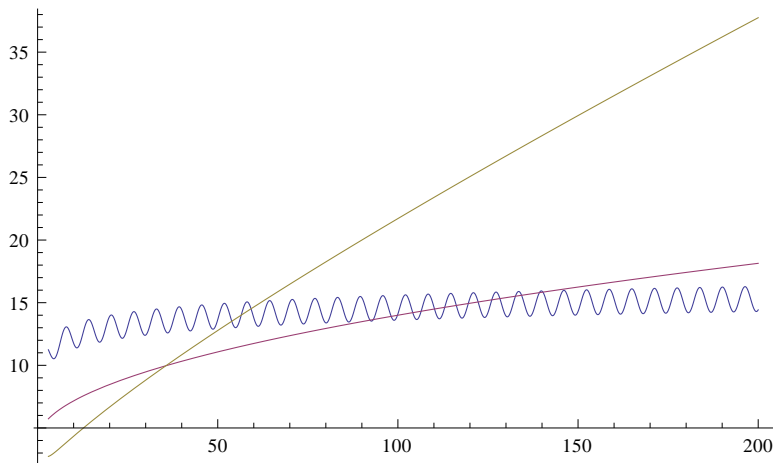
$$\text{Log}[n] + \text{Sin}[n] + 10,$$

$$\sqrt{n} + 4, \text{ and}$$

$$n / \text{Log}[n],$$

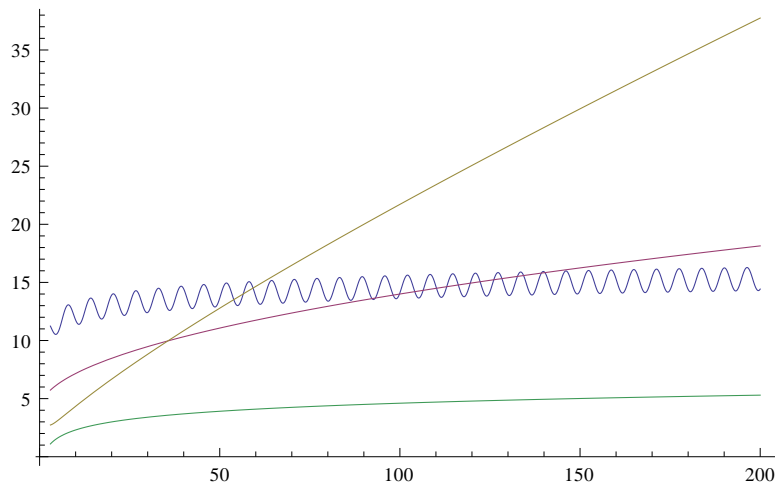
where n is the size of an input I .

`Plot[Tooltip[{ Log[n] + Sin[n] + 10, $\sqrt{n} + 4$, n / Log[n], }], {n, 3, 200}]`



`FunctionLog[n]` is a lower bound of all three.

```
Plot[Tooltip[{ Log[n] + Sin[n] + 10,  $\sqrt{n} + 4$ , n / Log[n], Log[n]}], {n, 3, 200}]
```



```
Limit[(Log[n] + Sin[n] + 10) / Log[n], n -> ∞]
```

```
1
```

```
Limit[ $\frac{\sqrt{n} + 4}{\text{Log}[n]}$ , n -> ∞]
```

```
∞
```

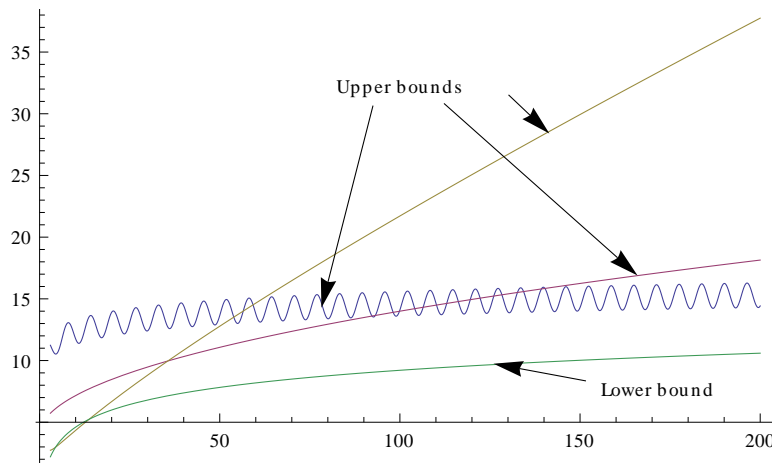
```
Limit[ $\frac{n / \text{Log}[n]}{\text{Log}[n]}$ , n -> ∞]
```

```
∞
```

So, $\text{Log}[n]$ is a lower bound on the time necessary to solve the problem Q (I).

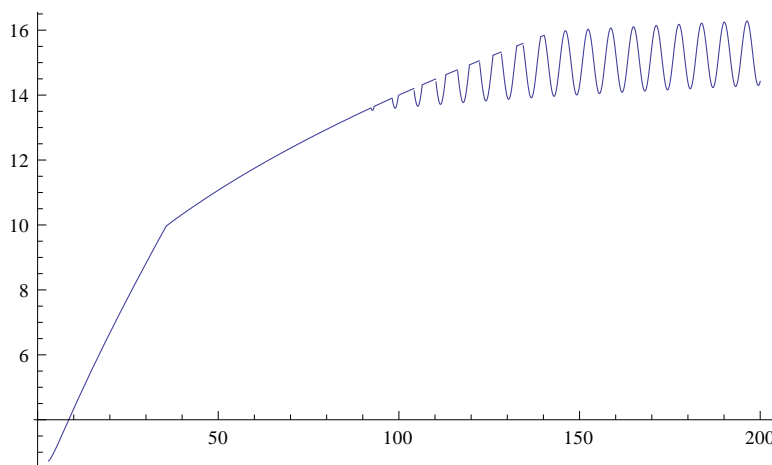
Each of the runnig times if problem' s solutions are (automatically) upper bounds on the time necessary to solve the problem Q (I).

```
Plot[Tooltip[{ Log[n] + Sin[n] + 10,  $\sqrt{n} + 4$ , n / Log[n], 2 Log[n]}], {n, 3, 200}]
```



Here is an improved (smaller, that is) upper bound for Q :

```
Plot[Tooltip[Min[Log[n] + Sin[n] + 10,  $\sqrt{n + 4}$ , n / Log[n]]], {n, 3, 200}]
```



So, if there were a solution that had worst-case running time $\text{Log}[n]$ then such a solution would be worst-case optimal.

Average-case analysis is similar.

Example : FindMax.

Problem $Q(I)$: Given an unsorted integer array I of size n , find an index of the largest element of I , using comparisons of elements of array as the only means of deciding which one it is.

$T(n)$ - the worst-case runningtime for the problem measured as the number of comparisons that are necessary to solve $Q(I)$ for any input I of size n .

Lower bound on $T(n)$.

Assume all elements of I are different.

The worst-case scenario will automatically be at least as bad as this.

There are $(n-1)$ non-maximal elements of I , and the algorithm must "know" who they are.

The algorithm "knows" that an element x of I is non-maximal iff x lost at least one comparison to some other element of I .

Each comparison leaves one loser element.

An algorithm that performed no more than $(n-2)$ comparisons identified no more than $(n-2)$ losers.

So, at least 2 elements are non-losers, each of which may be the maximal one.

Hence, at least $(n-1)$ comparisons are needed.

So,

$$f(n) = n - 1$$

is a lower bound on the worst-case runningtime of (any solution of) $Q(I)$.

The worst-case runningtime of linear search is (automatically) an upper bound on the worst-case

Linear search finds max element of I after $(n-1)$ comparisons

Hence, the worst-case runningtime of linear search is both a lower bound and an upper bound on the worst-case runningtime for $Q(I)$.

In other words, linear search is a worst-case optimal solution of $Q(I)$ in the class of algorithms that make their decisions based only on comparisons of keys.